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Advanced Computing and Communication Technologies - Ramesh K Choudhary 2016-06-09 This book highlights a collection of high-quality peer-reviewed research papers presented at the Ninth International Conference on Advanced Computing & Communication Technologies (ICACCT-2015) held at Asia Pacific Institute of Information Technology, Panipat, India during 27–29 November 2015. The book discusses a wide variety of industrial, engineering and scientific applications of the emerging techniques. Researchers from academia and industry present their original work and exchange ideas, information, techniques and applications in the field of Advanced Computing and Communication Technology.

Handbook of Research on Advanced Mechatronic Systems and Intelligent Robotics - Habib, Maki K. 2019-07-26 Advanced research in the field of mechatronics and robotics represents a unifying interdisciplinary and intelligent engineering science paradigm. It is a holistic, concurrent, and interdisciplinary engineering science that identifies novel possibilities of synergizing and fusing different disciplines. The Handbook of Research on Advanced Mechatronic Systems and Intelligent Robotics is a collection of innovative research on the methods and applications of knowledge in both theoretical and practical skills of intelligent robotics and mechatronics. While highlighting topics including green technology, machine learning, and virtual manufacturing, this book is ideally designed for researchers, students, engineers, and computer practitioners seeking current research on developing innovative ideas for intelligent robotics and autonomous and smart interdisciplinary mechatronic products.

Recent Trends in Wave Mechanics and Vibrations - S. Chakraverty 2019-11-12 This book consists of select proceedings of the National Conference on Wave Mechanics and Vibrations (WMVC 2018). It covers recent developments and cutting-edge methods in wave mechanics and vibrations applied to a wide range of engineering problems. The book presents analytical and computational studies in structural mechanics, seismology and earthquake engineering, mechanical engineering, aeronautics, robotics and nuclear engineering among others. This book can be useful for students, researchers, and professionals interested in the wide-ranging applications of wave mechanics and vibrations.

Soft-Material Robotics - Liyu Wang 2017-04-12 Introduces the fundamentals aspects of the topic from history, modelling, control, and system integration. The last decade has witnessed an increasing interest in the more active use of soft materials in robotic systems. Having a soft body like the ones in biological systems can potentially provide a robot with superior capabilities.

Grippers in Motion - Andreas Wolf 2006-02-08 Grippers in Motion provides a comprehensive, practice-oriented guide to the fascinating details of automation processes involving gripping and manipulation. This intriguing and colorful book leads the reader from the history of automation

and robotics to the fundamentals of the gripping process as well as the interaction of the gripping process with individual workpieces. Boundary conditions and initial situation of the gripping process are defined, and how subsequent motion follows gripping is shown. The implementation of these motion processes, from simple linear motions to the kinematics of multiple axes, is illustrated in a practical way. This practical introduction motivates students and even professionals to learn more about the world of robotic grippers. Grippers in Motion includes a spectrum of real-world applications demonstrating the possibilities and varieties of automation in practice.

Recent Trends in Mechatronics Towards Industry 4.0 - Ahmad Fakhri Ab. Nasir 2021-07-15
This book presents part of the iM3F 2020 proceedings from the Mechatronics track. It highlights key challenges and recent trends in mechatronics engineering and technology that are non-trivial in the age of Industry 4.0. It discusses traditional as well as modern solutions that are employed in the multitude spectra of mechatronics-based applications. The readers are expected to gain an insightful view on the current trends, issues, mitigating factors as well as solutions from this book.

Robotics - Bruno Siciliano 2010-08-20
Based on the successful Modelling and Control of Robot Manipulators by Sciavicco and Siciliano (Springer, 2000), Robotics provides the basic know-how on the foundations of robotics: modelling, planning and control. It has been expanded to include coverage of mobile robots, visual control and motion planning. A variety of problems is raised throughout, and the proper tools to find engineering-oriented solutions are introduced and explained. The text includes coverage of fundamental topics like kinematics, and trajectory planning and related technological aspects including actuators and sensors. To impart practical skill, examples and case studies are carefully worked out and interwoven through the text, with frequent resort to simulation. In addition, end-of-chapter exercises are proposed, and the book is accompanied by an electronic solutions manual containing the MATLAB® code for computer problems; this is available free of charge to those adopting this volume as a textbook for courses.

Mechanism Design for Robotics - Alessandro Gasparetto 2018-08-30
This volume contains the Proceedings of the 4th IFToMM Symposium on Mechanism Design for Robotics, held in Udine, Italy, 11-13 September, 2018. It includes recent advances in the design of mechanisms and their robotic applications. It treats, among others, the following topics: mechanism design, mechanics of robots, parallel manipulators, actuators and their control, linkage and industrial manipulators, innovative mechanisms/robots and their applications. This book can be used by students, researchers and engineers in the relevant areas of mechanisms, machines and robotics.

Proceedings - American Society for Engineering Education. Conference 1990

Intelligent Systems and Applications - Kohei Arai
This book presents Proceedings of the 2021 Intelligent Systems Conference which is a remarkable collection of chapters covering a wider range of topics in areas of intelligent systems and artificial intelligence and their applications to the real world. The conference attracted a total of 496 submissions from many academic pioneering researchers, scientists, industrial engineers, and students from all around the world. These submissions underwent a double-blind peer-review process. Of the total submissions, 180 submissions have been selected to be included in these proceedings. As we witness exponential growth of computational intelligence in several directions and use of intelligent systems in everyday applications, this book is an ideal resource for reporting latest innovations and future of AI. The chapters include theory and application on all aspects of artificial intelligence, from classical to intelligent scope. We hope that readers find the book interesting and valuable; it provides the state-of-the-art intelligent methods and techniques for solving real-world problems along with a vision of the future research.

Mechanical and Electronics Engineering -

Advances in Mechanism and Machine Science - Tadeusz Uhl 2019-06-13
This book gathers the proceedings of the 15th

IFToMM World Congress, which was held in Krakow, Poland, from June 30 to July 4, 2019. Having been organized every four years since 1965, the Congress represents the world's largest scientific event on mechanism and machine science (MMS). The contributions cover an extremely diverse range of topics, including biomechanical engineering, computational kinematics, design methodologies, dynamics of machinery, multibody dynamics, gearing and transmissions, history of MMS, linkage and mechanical controls, robotics and mechatronics, micro-mechanisms, reliability of machines and mechanisms, rotor dynamics, standardization of terminology, sustainable energy systems, transportation machinery, tribology and vibration. Selected by means of a rigorous international peer-review process, they highlight numerous exciting advances and ideas that will spur novel research directions and foster new multidisciplinary collaborations.

Robot Grippers - Gareth J. Monkman 2007-02-27 Since robotic prehension is widely used in all sectors of manufacturing industry, this book fills the need for a comprehensive, up-to-date treatment of the topic. As such, this is the first text to address both developers and users, dealing as it does with the function, design and use of industrial robot grippers. The book includes both traditional methods and many more recent developments such as micro grippers for the optolectronics industry. Written by authors from academia, industry and consulting, it begins by covering the four basic categories of robotic prehension before expanding into sections dealing with endeffector design and control, robotic manipulation and kinematics. Later chapters go on to describe how these various gripping techniques can be used for a common industrial aim, with details of related topics such as: kinematics, part separation, sensors, tool excahnge and compliance. The whole is rounded off with specific examples and case studies. With more than 570 figures, this practical book is all set to become the standard for advanced students, researchers and manufacturing engineers, as well as designers and project managers seeking practical descriptions of robot endeffectors and their applications.

Compliance Control Analysis of a Two-Axis

Robotic Gripper - Somdutta Sinha 2015-02-09 In the presented work, the author has discussed the characterization procedure of artificial human-hand replaced by robotic arm.The book includes the inception of robotic era & its wide possible applications in 3-D block of various shapes & sizes lifting and movements in two-coordinate axis.During the accomplishment of the work, she has tried to explain various control systems required for a dextrous 2-axis robotic arm to function.Simulation works in MATLAB, C++ and BasicX-24 Stamp.Along with this, various established results obtained are highlighted and analyzed analytically.The presented topics also include the detailed mechanism and realization for the manipulation of robot-hand for comfortable operation.The issues related to development of prosthetic hand finds the appropriate substitute under specific conditions in real time situation.The task gets complicated in terms of degree of freedom for movement & accessing the object towards exactness of the need based.The process of fabrication is realized using IIR & FIR digital filters.The system's stability has been given a high priority for the design of such robotic arms to make the same more adaptive in various real time situati

Models, Methods, Concepts & Applications of the Analytic Hierarchy Process - Thomas L. Saaty 2012-04-11 The Analytic Hierarchy Process (AHP) is a prominent and powerful tool for making decisions in situations involving multiple objectives. Models, Methods, Concepts and Applications of the Analytic Hierarchy Process, 2nd Edition applies the AHP in order to solve problems focused on the following three themes: economics, the social sciences, and the linking of measurement with human values. For economists, the AHP offers a substantially different approach to dealing with economic problems through ratio scales. Psychologists and political scientists can use the methodology to quantify and derive measurements for intangibles. Meanwhile researchers in the physical and engineering sciences can apply the AHP methods to help resolve the conflicts between hard measurement data and human values. Throughout the book, each of these topics is explored utilizing real life models and

examples, relevant to problems in today's society. This new edition has been updated and includes five new chapters that includes discussions of the following: - The eigenvector and why it is necessary - A summary of ongoing research in the Middle East that brings together Israeli and Palestinian scholars to develop concessions from both parties - A look at the Medicare Crisis and how AHP can be used to understand the problems and help develop ideas to solve them.

An Economic Analysis on Automated Construction Safety - Rita Yi Man Li
2017-08-09
This book addresses information technologies recently applied in the field of construction safety. Combining case studies, literature reviews and interviews to study the issue, it presents cutting-edge applications of various information technologies (ITs) in construction in different parts of the world, together with a wealth of figures, tables and examples. Though primarily intended for researchers and experts in the field, the book will also benefit graduate students.

Technological Advancement Through Canada-U.S.-global Interchange - American Society for Engineering Education. Conference 1990

Engineering Applications for New Materials and Technologies - Andreas Öchsner
2018-01-25
This book discusses the expertise, skills, and techniques needed for the development of new materials and technologies. It focuses on finite element and finite volume methods that are used for engineering simulations, and present many state-of-the-art applications and advances to highlight these methods' importance. For example, modern joining technologies can be used to fabricate new compound or composite materials, even those formed from dissimilar component materials. These composite materials are often exposed to harsh environments, must deliver specific characteristics, and are primarily used in automotive and marine technologies, i.e., ships, amphibious vehicles, docks, offshore structures, and even robots. To achieve the desired material performance, computer-based engineering tools are widely used for simulation, data evaluation, and design processes.

Robot Grippers - Gareth J. Monkman
2007-02-27
Since robotic prehension is widely used in all sectors of manufacturing industry, this book fills the need for a comprehensive, up-to-date treatment of the topic. As such, this is the first text to address both developers and users, dealing as it does with the function, design and use of industrial robot grippers. The book includes both traditional methods and many more recent developments such as micro grippers for the optolectronics industry. Written by authors from academia, industry and consulting, it begins by covering the four basic categories of robotic prehension before expanding into sections dealing with endeffector design and control, robotic manipulation and kinematics. Later chapters go on to describe how these various gripping techniques can be used for a common industrial aim, with details of related topics such as: kinematics, part separation, sensors, tool excahnge and compliance. The whole is rounded off with specific examples and case studies. With more than 570 figures, this practical book is all set to become the standard for advanced students, researchers and manufacturing engineers, as well as designers and project managers seeking practical descriptions of robot endeffectors and their applications.

Journal of Rehabilitation Research and Development - 1983

Informatics in Control, Automation and Robotics - Oleg Gusikhin 2019-10-25
The goal of this book is to familiarize readers with the latest research on, and recent advances in, the field of Informatics in Control, Automation and Robotics. It gathers a selection of papers highlighting the state-of-the-art in Intelligent Control Systems, Optimization, Robotics and Automation, Signal Processing, Sensors, Systems Modelling and Control. Combining theoretical aspects with practical applications, the book offers a well-balanced overview of the latest achievements, and will provide researchers, engineers and PhD students with both a vital update and new inspirations for their own research.

Robotic Fabrication in Architecture, Art and Design 2018 - Jan Willmann 2018-08-25

The book presents research from Rob|Arch 2018, the fourth international conference on robotic fabrication in architecture, art, and design. In capturing the myriad of scientific advances in robotics fabrication that are currently underway – such as collaborative design tools, computerised materials, adaptive sensing and actuation, advanced construction, on-site and cooperative robotics, machine-learning, human-machine interaction, large-scale fabrication and networked workflows, to name but a few – this compendium reveals how robotic fabrication is becoming a driver of scientific innovation, cross-disciplinary fertilization and creative capacity of an unprecedented kind.

Intelligence and Safety for Humanoid Robots: Design, Control, and Applications - Zhihong Tian 2022-02-07

CONSTRUCTING ROBOT BASES,1/ - This title gives an in-depth look at constructing robot bases - the ultimate guide for intermediate builders.

Intel Galileo and Intel Galileo Gen 2 - Manoel Ramon 2014-12-31
Intel® Galileo and Intel® Galileo Gen 2: API Features and Arduino Projects for Linux Programmers provides detailed information about Intel® Galileo and Intel® Galileo Gen 2 boards for all software developers interested in Arduino and the Linux platform. The book covers the new Arduino APIs and is an introduction for developers on natively using Linux. Author Manoel Carlos Ramon is a member of the Intel Galileo development team; in this book he draws on his practical experience in working on the Galileo project as he shares the team's findings, problems, fixes, workarounds, and techniques with the open source community. His areas of expertise are wide-ranging, including Linux-embedded kernel and device drivers, C/C++, Java, OpenGL, Assembler, Android NDK/SDK/ADK, and 2G/3G/4G modem integration. He has more than 17 years of experience in research and development of mobile devices and embedded circuits. His personal blog about programming is BytesThink (www.bytesthink.com).

Mechanism Design for Robotics - Marco Ceccarelli 2019-06-21
MEDER 2018, the IFToMM International Symposium on Mechanism Design for Robotics, was the fourth event in a series that was started in 2010 as a specific conference activity on mechanisms for robots. The aim of the MEDER Symposium is to bring researchers, industry professionals, and students together from a broad range of disciplines dealing with mechanisms for robots, in an intimate, collegial, and stimulating environment. In the 2018 MEDER event, we received significant attention regarding this initiative, as can be seen by the fact that the Proceedings contain contributions by authors from all around the world. The Proceedings of the MEDER 2018 Symposium have been published within the Springer book series on MMS, and the book contains 52 papers that have been selected after review for oral presentation. These papers cover several aspects of the wide field of robotics dealing with mechanism aspects in theory, design, numerical evaluations, and applications. This Special Issue of Robotics (https://www.mdpi.com/journal/robotics/special_issues/MDR) has been obtained as a result of a second review process and selection, but all the papers that have been accepted for MEDER 2018 are of very good quality with interesting contents that are suitable for journal publication, and the selection process has been difficult.

Advances in Manufacturing Systems - Shailendra Kumar 2021-02-25
This book presents the select proceedings of the International Conference on Recent Advances in Manufacturing (RAM 2020). The volume focuses on latest research trends in manufacturing systems such as CAE, CAD/CAM, robotics and automation, reverse engineering, resource planning and simulation, computer-integrated manufacturing (CIM) systems, product life-cycle management, collaborative engineering, process monitoring control and traceability technologies, supply chain management, environment risk analysis, and manufacturing systems of renewable energy devices. The topics covered also include emerging fields of the fourth industrial revolution such cyber physical systems and cyber security, and wireless sensors and sensor networks for manufacturing. This book will be of interest to researchers and practitioners interested in latest developments in the field of manufacturing systems.

Fantastic Five Fictions - Vairam 2012-10-19
This book deals about blindly following the Western way of life since according to ancient texts of Hinduism, the four races which existed in Jam-bu Dweeb in which one of the continent Bharath. In that four pure races, white, red, yellow, and black, which mixed to form Asians, Chinese, European, and African races, which respectively are thinkers (white), red (administrators and executors), yellow (wealth creators), black (good and excellent working people). Therefore, after the mix, everybody slowly follows Western civilization without knowing the repercussion of terrorists, financial crisis, breaking of family, and easy way of making money by fraudulent means. All the five fiction stories revolve around these problems.

Intelligent Robotics and Applications - Honghai Liu 2022-09-04
The 4-volume set LNAI 13455 - 13458 constitutes the proceedings of the 15th International Conference on Intelligent Robotics and Applications, ICIRA 2022, which took place in Harbin China, during August 2022. The 284 papers included in these proceedings were carefully reviewed and selected from 442 submissions. They were organized in topical sections as follows: Robotics, Mechatronics, Applications, Robotic Machining, Medical Engineering, Soft and Hybrid Robots, Human-robot Collaboration, Machine Intelligence, and Human Robot Interaction.

Proceedings - American Society for Engineering Education 1990

Advancement in Materials, Manufacturing and Energy Engineering, Vol. II - Puneet Verma 2022-01-18
This book (Vol. II) presents select proceedings of the conference on "Advancement in Materials, Manufacturing, and Energy Engineering (ICAMME 2021)." It discusses the latest materials, manufacturing processes, evaluation of materials properties for the application in automotive, aerospace, marine, locomotive, and energy sectors. The topics covered include advanced metal forming, bending, welding and casting techniques, recycling and re-manufacturing of materials and components, materials processing, characterization and applications, materials, composites and polymer manufacturing, powder metallurgy and ceramic forming, numerical modeling and simulation, advanced machining processes, functionally graded materials, non-destructive examination, optimization techniques, engineering materials, heat treatment, material testing, MEMS integration, energy materials, bio-materials, metamaterials, metallography, nanomaterial, SMART materials, bioenergy, fuel cell, and superalloys. The book will be useful for students, researchers, and professionals interested in interdisciplinary topics in the areas of materials, manufacturing, and energy sectors.

Recent Advances in Materials and Modern Manufacturing - I. A. Palani 2022
This book presents the select proceedings of the fourth International Conference on Advanced Materials and Modern Manufacturing (ICAMMM 2021). It covers broad areas such as advanced mechanical engineering, material science and manufacturing process. Various topics discussed in this book include green manufacturing, green materials, Industry 4.0, additive manufacturing, precision engineering, sustainability, manufacturing operations management and so on. Given its contents, the book will be useful for students, researchers, engineers and professionals working in the area of mechanical engineering and its allied fields.

Foundations of Deep Reinforcement Learning - Laura Graesser 2019-11-20
The Contemporary Introduction to Deep Reinforcement Learning that Combines Theory and Practice Deep reinforcement learning (deep RL) combines deep learning and reinforcement learning, in which artificial agents learn to solve sequential decision-making problems. In the past decade deep RL has achieved remarkable results on a range of problems, from single and multiplayer games—such as Go, Atari games, and DotA 2—to robotics. Foundations of Deep Reinforcement Learning is an introduction to deep RL that uniquely combines both theory and implementation. It starts with intuition, then carefully explains the theory of deep RL algorithms, discusses implementations in its companion software library SLM Lab, and finishes with the practical details of getting deep RL to work. This guide is ideal for both computer science students and software engineers who are familiar with basic machine learning

concepts and have a working understanding of Python. Understand each key aspect of a deep RL problem Explore policy- and value-based algorithms, including REINFORCE, SARSA, DQN, Double DQN, and Prioritized Experience Replay (PER) Delve into combined algorithms, including Actor-Critic and Proximal Policy Optimization (PPO) Understand how algorithms can be parallelized synchronously and asynchronously Run algorithms in SLM Lab and learn the practical implementation details for getting deep RL to work Explore algorithm benchmark results with tuned hyperparameters Understand how deep RL environments are designed Register your book for convenient access to downloads, updates, and/or corrections as they become available. See inside book for details.

Proceedings of Seventh International Congress on Information and Communication Technology - Xin-She Yang 2022-09-03
This book gathers selected high-quality research papers presented at the Seventh International Congress on Information and Communication Technology, held at Brunel University, London, on February 21–24, 2022. It discusses emerging topics pertaining to information and communication technology (ICT) for managerial applications, e-governance, e-agriculture, e-education and computing technologies, the Internet of Things (IoT) and e-mining. Written by respected experts and researchers working on ICT, the book offers a valuable asset for young researchers involved in advanced studies. The work is presented in four volumes.

Recent Advances in Manufacturing, Automation, Design and Energy Technologies - Sendhil Kumar Natarajan 2021-10-11
This book comprises the proceedings of the 1st International Conference on Future Technologies in Manufacturing, Automation, Design and Energy 2020. The contents of this volume focus on recent technological advances in the field of manufacturing, automation, design and energy. Some of the topics covered include additive manufacturing, renewable energy resources, design automation, process automation and monitoring, etc. This volume will prove a valuable resource for those in academia and industry.

Proceedings of International Conference on Industrial Instrumentation and Control - Subhasis Bhaumik 2022-02-15
This book is a collection of selected high-quality research papers presented at the International Conference on Industrial Instrumentation and Control (ICI2C 2021), organized by the Department of Applied Electronics & Instrumentation Engineering, RCC Institute of Information Technology, Kolkata, India, during 20–August 22, 2021. It includes novel and innovative work from experts, practitioners, scientists and decision-makers from academia and industry. It covers topics such as instrumentation application in industry, instrumentation in electrical applications and instrumentation in recent trends with computation approach.

Towards Sustainable Customization: Bridging Smart Products and Manufacturing Systems - Ann-Louise Andersen 2021-12-02
This book features state-of-the-art contributions from two well-established conferences: Changeable, Agile, Reconfigurable and Virtual Production Conference (CARV2020) and Mass Customization and Personalization Conference (MCPC2020). Together, they focus on the joint design, development, and management of products, production systems, and business for sustainable customization and personalization. The book covers a large range of topics within this domain, ranging from industrial success factors to original contributions within the field.

Advances in Robot Design and Intelligent Control - Aleksandar Rodić 2016-11-26
This book presents the proceedings of the 25th International Conference on Robotics in Alpe-Adria-Danube Region, RAAD 2016 held in Belgrade, Serbia, on June 30th–July 2nd, 2016. In keeping with the tradition of the event, RAAD 2016 covered all the important areas of research and innovation in new robot designs and intelligent robot control, with papers including Intelligent robot motion control; Robot vision and sensory processing; Novel design of robot manipulators and grippers; Robot applications in manufacturing and services; Autonomous systems, humanoid and walking robots; Human–robot interaction and collaboration;

Cognitive robots and emotional intelligence; Medical, human-assistive robots and prosthetic design; Robots in construction and arts, and Evolution, education, legal and social issues of robotics. For the first time in RAAD history, the themes cloud robots, legal and ethical issues in robotics as well as robots in arts were included in the technical program. The book is a valuable resource for researchers in fields of robotics, engineers who implement robotic solutions in manufacturing, services and healthcare, and master's and Ph.D. students working on robotics projects.

Advanced Path Planning for Mobile Entities - Rastislav Róka 2018-09-26
The book Advanced Path Planning for Mobile Entities provides a platform for practicing researchers, academics, PhD students, and other scientists to design, analyze, evaluate, process, and implement diversiform issues of path planning, including algorithms for multipath and mobile planning and path planning for mobile robots. The nine chapters of the book demonstrate capabilities of advanced path planning for mobile entities to solve scientific and engineering problems with varied degree of complexity.

Elements of Robotics - Mordechai Ben-Ari 2017-10-25
This open access book bridges the gap between playing with robots in school and studying robotics at the upper undergraduate and graduate levels to prepare for careers in industry and research. Robotic algorithms are presented formally, but using only mathematics known by high-school and first-year college students, such as calculus, matrices and probability. Concepts and algorithms are explained through detailed diagrams and calculations. Elements of Robotics presents an overview of different types of robots and the components used to build robots, but focuses on robotic algorithms: simple algorithms like odometry and feedback control, as well as algorithms for advanced topics like localization, mapping, image processing, machine learning and swarm robotics. These algorithms are demonstrated in simplified contexts that enable detailed computations to be performed and feasible activities to be posed. Students who study these simplified demonstrations will be well prepared for advanced study of robotics. The algorithms are presented at a relatively abstract level, not tied to any specific robot. Instead a generic robot is defined that uses elements common to most educational robots: differential drive with two motors, proximity sensors and some method of displaying output to the user. The theory is supplemented with over 100 activities, most of which can be successfully implemented using inexpensive educational robots. Activities that require more computation can be programmed on a computer. Archives are available with suggested implementations for the Thymio robot and standalone programs in Python.